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# Vibration Control Using Semi-Active Force Generators

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A type of force generator which can respond to general feedback signals from a vibrating system in order to control the vibration but which does not require the power supply of a servomechanism is described. Computer simulation studies show that performance comparable to that of fully active vibration control systems can be achieved with the semi-active type of device. Physical embodiments of the concept are discussed and compared to hardware used in active and passive vibration control systems.

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device is mainly used to control the vibration of the direction. Figure 1. Installation diagram of magnetic fluid damping device for machine tool. No. 8 — 2015. Therefore, through the magneto-rheological damper to the semi-active control of machine tool vibration system, taking a certain control algorithm, can adjust the damping ratio of the system, and real-time achieve well vibration damping effect. 3. Design of Fuzzy Controller 3.1. The use of semi-active control schemes for mitigation of traffic-induced bridge vibrations has been both analytically, experimentally, and field tested. Patten et al. [20] investigated analytically and experimentally the effectiveness of a semi-active vibration absorber on a 40 feet (12.2 meter) single-lane bridge they constructed. An analytical study conducted by Christenson showed a reduction of maximum midspan displacement of 50% can be achieved with a semi-active control scheme, while only a 31% reduction was achieved using a passive damper control method [3]. Semi-active control methods for reducing vertical vibration are a promising solution that warrants further investigate and research. @article{Karnopp1974VibrationCU, title={Vibration Control Using Semi-Active Force Generators}, author={D. Karnopp and M. J. Crosby and R. A. Harwood}, journal={Journal of Engineering for Industry}, year={1974}, volume={96}, pages={619-626} }. D. Karnopp, M. J. Crosby, R. A. Harwood. Published 1974. Engineering. Journal of Engineering for Industry. 5,020,781 6/1991 Huang . 267/136 5,248,015 9/1993 Yoshioka et al. .